|  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- |
|  | | COMMISSIONING STATEMENT Robot Project – Modular Field BDR | | |  | |
|  | |  | | |
| Project Name | | | Name | |
| Company Name | | |  | |
| Team Members | | | Section | |

**TEST RESULTS:**

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **Pass** | | **Fail** | | **N/A** | |
| **Robot accepts the program.** | | □ | | □ | | □ | |
| **Robot's dimensions: 25cm x 25cm base/ 20cm height** | | □ | | □ | | □ | |
|  | |  | |  | |  | |
| **Robot:** | |  | |  | |  | |
| 1. Navigates to the switch. | | □ | | □ | | □ | |
| 1. Disarms the bomb. | | □ | | □ | | □ | |
| 1. Travels back to the starting point. | | □ | | □ | | □ | |
|  | |  | |  | |  | |
|  | |  | |  | |  | |
|  | |  | |  | |  | |
| **Extra Credit:** | |  | |  | |  | |
|  | | **Achieved** | | **Points** | |
| Robot disrupts triangulation device **(at least 2 devices)** | | □ 🡪 | | **3** | |
| Robot retrieve and bring back device to start area **(at least 1)** | | □ 🡪 | | **6** | |
|  | |

Acceptance Test has been successfully completed. The project’s development is concluded and the product is approved for commercial implementation.

|  |  |  |
| --- | --- | --- |
|  |  | |
| Team Member | | Date |
| Team Member | | Date |
| Team Member | | Date |  |
| Commissioned by | | Date |  |